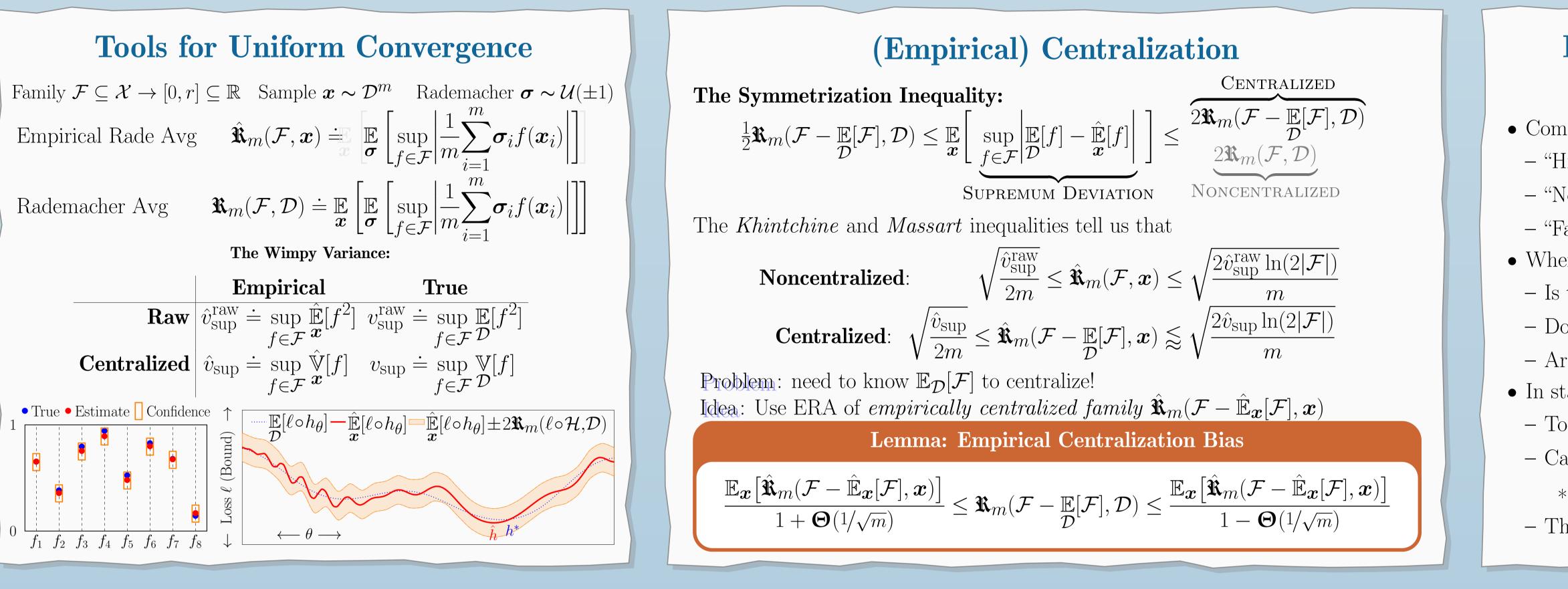
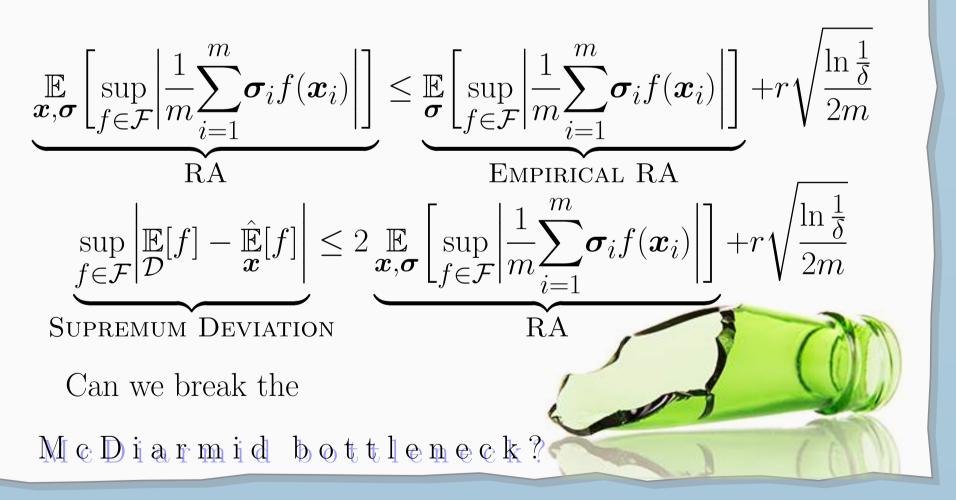
# SHARP UNIFORM CONVERGENCE BOUNDS THROUGH EMPIRICAL CENTRALIZATION

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### **Standard McDiarmid Bounds**



### **Target: Bousquet's Inequality**

We want dependence on  $v_{sup}$ , not  $v_{sup}^{raw}$  or  $r^2$ In particular, we want to match *Bousquet's inequality*:

 $\sup_{f \in \mathcal{F}} \left| \underset{\mathcal{D}}{\mathbb{E}}[f] - \hat{\underset{\boldsymbol{x}}{\mathbb{E}}}[f] \right| \leq 2 \Re_m(\mathcal{F}, \mathcal{D}) + \frac{r \ln \frac{1}{\delta}}{3m} + \sqrt{\frac{2 \left( v_{\sup} + 4r \Re_m(\mathcal{F}, \mathcal{D}) \right) \ln \frac{1}{\delta}}{m}}$ 

We show that  $\hat{v}_{sup}$  is sufficient to sharply bound  $v_{sup}$ 

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## With High Probability

**Theorem: Concentration of Empirically Centralized RAs** 

With probability at least  $1 - \delta$  over choice of  $\boldsymbol{x}$ :

$$\mathbb{E}_{\boldsymbol{x}} \left[ \hat{\boldsymbol{\mathfrak{K}}}_{m} (\mathcal{F} - \hat{\mathbb{E}}_{\boldsymbol{x}} [\mathcal{F}], \boldsymbol{x}) \right] \leq \hat{\boldsymbol{\mathfrak{K}}}_{m} (\mathcal{F} - \hat{\mathbb{E}}_{\boldsymbol{x}} [\mathcal{F}], \boldsymbol{x}) \\
+ O \left( \frac{r \ln \frac{1}{\delta}}{m} + \sqrt{\frac{4r(\hat{\boldsymbol{\mathfrak{K}}}_{m} (\mathcal{F} - \hat{\mathbb{E}}_{\boldsymbol{x}} [\mathcal{F}], \boldsymbol{x}) + r/\sqrt{m}) \ln \frac{1}{\delta}}{m}} \right)$$

The Monte-Carlo Method: Given  $\boldsymbol{\sigma} \in (\pm 1)^{n \times m}$ , define  $\hat{\mathbf{x}}_{m}^{n}(\mathcal{F}, \boldsymbol{x}, \boldsymbol{\sigma}) \doteq \frac{1}{n} \sum_{i=1}^{n} \sup_{f \in \mathcal{F}} \left| \frac{1}{m} \sum_{i=1}^{m} \boldsymbol{\sigma}_{j,i} f(\boldsymbol{x}_{i}) \right|$ 

### **Theorem: Monte-Carlo Error Bounds**

With probability at least  $1 - \delta$  over choice of  $\boldsymbol{\sigma} \sim \mathcal{U}^{n \times m}(\pm 1)$ :

$$\hat{\mathbf{\mathfrak{K}}}_{m}(\mathcal{F},\boldsymbol{x}) \leq \hat{\mathbf{\mathfrak{K}}}_{m}^{n}(\mathcal{F},\boldsymbol{x},\boldsymbol{\sigma}) + \frac{2r\ln\frac{1}{\delta}}{3nm} + \sqrt{\frac{4\hat{v}_{\sup}^{\mathrm{raw}}\ln\frac{1}{\delta}}{nm}}$$

$$\hat{\mathbf{\mathfrak{K}}}_{m}(\mathcal{F}-\hat{\mathbb{E}}_{\boldsymbol{x}}[\mathcal{F}],\boldsymbol{x}) \leq \hat{\mathbf{\mathfrak{K}}}_{m}^{n}(\mathcal{F}-\hat{\mathbb{E}}_{\boldsymbol{x}}[\mathcal{F}],\boldsymbol{x},\boldsymbol{\sigma}) + \frac{4r\ln\frac{1}{\delta}}{3nm} + \sqrt{\frac{4\hat{v}_{\sup}\ln\frac{1}{\delta}}{nm}}$$

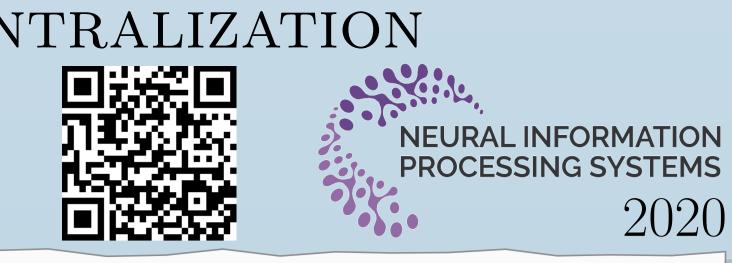
### **Comparative Analysis of Tail Bounds**

 $2\hat{\mathbf{k}}_{m}\left(\mathcal{F},\boldsymbol{x}
ight)$ 

- Implicit dependence of  $\Omega \sqrt{\frac{v_{sup}^{raw}}{m}}$

$$\frac{2\hat{\mathbf{x}}_{m}(\mathcal{F}-\hat{\mathbb{E}}_{\boldsymbol{x}}[\mathcal{F}],\boldsymbol{x})}{1-\boldsymbol{\Theta}\sqrt{\frac{1}{m}}}+\boldsymbol{O}\left(\frac{r\ln\frac{1}{\delta}}{m}+\sqrt{\frac{(v_{\sup}+r\mathbf{x}_{m}(\mathcal{F}-\mathbb{E}_{\mathcal{D}}[\mathcal{F}],\mathcal{D})+\frac{r^{2}}{\sqrt{m}})\ln\frac{1}{\delta}}{m}}\right)$$

- Versus Localization



### **Perceived Problems with the Rademacher Average**

• Common criticisms of Rademacher averages

- "Highly theoretical tool"

- "Not useful in practice"

- "Fail to explain" generalization of popular ML methods • Where do these claims come from?

- Is the symmetrization inequality tight?

- Do we have sharp tail bounds on the empirical SD? - Are data-dependent bounds on  $\hat{\mathbf{X}}_m(\mathcal{F}, \boldsymbol{x})$  tight?

• In standard practice: **no, no, and no!** 

- To "fix" the bounds, we must repair *every part* of them - Can we match lower-bounds at every step?

\* Minimax mean-estimation bound:  $m \in \Omega \frac{v_{\sup} \ln \frac{1}{\delta}}{2c^2}$ - The loosest bound is the bottleneck!

• Prior Work: with probability at least  $1 - \delta$ , we may bound the SD as

+ O 
$$\left(\frac{r\ln\frac{1}{\delta}}{m} + \sqrt{\frac{(v_{\sup} + r \mathbf{\mathfrak{X}}_m(\mathcal{F}, \mathcal{D}))\ln\frac{1}{\delta}}{m}}\right)$$

- Prior work: Monte-Carlo requires  $n \in \mathbf{\Omega} \frac{r^2}{v^{\text{raw}}}$  trials - This work: n = 1 is asymptotically optimal

• This Work: With probability at least  $1 - \delta$ , we may bound the SD as

- All  $v_{sup}^{raw}$  dependence moved to  $v_{sup}$  dependence - Can substitute  $\hat{v}_{sup}$  and Monte-Carlo ERAs

- Complementary methods: *first* and *second* moment corrections - Localization often conflates *raw* and *centralized* variances